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lt;div>In LiDAR, laser light is sent from a source (transmitter)
and reflected from objects in the scene. The reflected
light is detected by the system receiver and the time of flight (TO) Tj T*□□BT /F1 12 Tf 50

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<div><div>The object-wise feature extractors project LiD
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2D networks. Then, they regress the region proposals to predict the
 3D bounding boxes.</div></div></div></div></div>&
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an>A Survey on Deep-Learning-Based LiDAR 3D Object Detection for ...</div><div>mdpi : ...</div></
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